

Package ‘propagate’

May 9, 2026

Type Package

LazyLoad no

LazyData no

Title Propagation of Uncertainty

Version 1.1-0

Date 2026-02-23

Maintainer Andrej-Nikolai Spiess <draspiess@gmail.com>

Description Propagation of uncertainty using higher-order Taylor expansion and Monte Carlo simulation. Calculations of propagated uncertainties are based on matrix calculus including covariance structure according to Arras 1998 <doi:10.3929/ethz-a-010113668> (first order), Wang & Iyer 2005 <doi:10.1088/0026-1394/42/5/011> (second order) and BIPM Supplement 1 (Monte Carlo) <doi:10.59161/JCGM101-2008>.

License GPL (>= 2)

Depends R (>= 4.0.0)

Imports Rcpp, minpack.lm, copula, hdf5r, crayon

LinkingTo Rcpp

NeedsCompilation yes

Repository CRAN

Date/Publication 2026-02-25 11:40:02 UTC

Author Andrej-Nikolai Spiess [aut, cre]

Contents

bigcor	2
cor2cov	4
datasets	5
fitDistr	7
interval	10
makeDat	13
makeDerivs	14
matrixStats	16

mixCov	17
moments	19
numDerivs	20
plot.propagate	21
predictNLS	22
propagate	25
rDistr	34
sobol	36
statVec	38
stochContr	39
summary.propagate	40
WelchSatter	42

Index	44
--------------	-----------

bigcor	<i>Creating very large correlation/covariance matrices</i>
--------	--

Description

The storage of a value in double format needs 8 bytes. When creating large correlation matrices, the amount of RAM might not suffice, giving rise to the dreaded *"cannot allocate vector of size ..."* error. For example, an input matrix with 50000 columns/100 rows will result in a correlation matrix with a size of 50000 x 50000 x 8 Byte / (1024 x 1024 x 1024) = 18.63 GByte, which still challenges most standard PCs. bigcor uses the framework of the 'hdf5r' package to store the correlation/covariance matrix in a file. The complete matrix is created by filling a large preallocated empty matrix with sub-matrices at the corresponding positions. See 'Details'.

Usage

```
bigcor(x, y = NULL, fun = c("cor", "cov"), size = 2000,
       verbose = TRUE, file = "result.h5", ...)
```

Arguments

x	the input matrix.
y	NULL (default) or a vector, matrix or data frame with compatible dimensions to x.
fun	create either a correlation or covariance matrix.
size	the n x n block size of the submatrices. 2000 has shown to be time-effective.
verbose	logical. If TRUE, information is printed in the console when running.
file	name (and possible path) of the created h5-file on disk.
...	other parameters to be passed to cor or cov .

Details

Calculates a correlation matrix \mathbf{R} or covariance matrix $\mathbf{\Sigma}$ using the following steps:

- 1) An input matrix \mathbf{X} with N columns is split into k equal size blocks (+ a possible remainder block) A_1, A_2, \dots, A_k of size n . The block size can be defined by the user, `size = 2000` is a good value because `cor` can handle this quite quickly (~ 400 ms). For example, if the matrix has 13796 columns, the split will be $A_1 = 1 \dots 2000$; $A_2 = 2001 \dots 4000$; $A_3 = 4001 \dots 6000$; $A_4 = 6000 \dots 8000$; $A_5 = 8001 \dots 10000$; $A_6 = 10001 \dots 12000$; $A_7 = 12001 \dots 13796$.
- 2) For all pairwise combinations of blocks $\binom{k}{2}$, the $n \times n$ correlation sub-matrix is calculated. If $y = \text{NULL}$, $\text{cor}(A_1, A_1), \text{cor}(A_1, A_2), \dots, \text{cor}(A_k, A_k)$, otherwise $\text{cor}(A_1, y), \text{cor}(A_2, y), \dots, \text{cor}(A_k, y)$.
- 3) The sub-matrices are transferred into a preallocated $N \times N$ empty matrix at the corresponding position (where the correlations would usually reside). To ensure symmetry around the diagonal, this is done twice in the upper and lower triangle. If y was supplied, a $N \times M$ matrix is filled, with $M = \text{number of columns in } y$.

Since the resulting matrix is in 'hdf5r' format, one has to subset to extract regions into normal `matrix`-like objects. See 'Examples'.

Value

The corresponding correlation/covariance matrix in 'hdf5r' format.

Author(s)

Andrej-Nikolai Spiess

References

<https://rmazing.wordpress.com/2013/02/22/bigcor-large-correlation-matrices-in-r/>

Examples

```
## Small example to prove similarity
## to standard 'cor'. We create a matrix
## by subsetting the complete 'hdf5r' matrix.
MAT <- matrix(rnorm(70000), ncol = 700)
h5file <- tempfile(fileext = ".h5")
COR1 <- bigcor(MAT, size = 500, fun = "cor", file = h5file)
h5 <- hdf5r::H5File$new(COR1, mode = "r")
COR1 <- h5[["matrix"]][,] # Read entire matrix
## COR1 <- h5[["matrix"]][1:1000, 1:1000] # would be submatrix
h5$close_all()
all.equal(COR1, cor(MAT)) # => TRUE
file.remove(h5file)
```

cor2cov

*Converting a correlation matrix into a covariance matrix***Description**

Converts a correlation matrix into a covariance matrix using variance information. It is therefore the opposite of [cov2cor](#).

Usage

```
cor2cov(C, var)
```

Arguments

C a symmetric numeric correlation matrix **C**.
var a vector of variances σ_n^2 .

Details

Calculates the covariance matrix Σ using a correlation matrix **C** and outer products of the standard deviations σ_n :

$$\Sigma = \mathbf{C} \cdot \sigma_n \otimes \sigma_n$$

Value

The corresponding covariance matrix.

Author(s)

Andrej-Nikolai Spiess

Examples

```
## Example in Annex H.2 from the GUM 2008 manual
## (see 'References'), simultaneous resistance
## and reactance measurement.
data(H.2)
attach(H.2)

## Original covariance matrix.
COV <- cov(H.2)
## extract variances
VAR <- diag(COV)

## cor2cov covariance matrix.
COV2 <- cor2cov(cor(H.2), VAR)

## Equal to original covariance matrix.
all.equal(COV2, COV)
```

datasets

Datasets from the GUM "Guide to the expression of uncertainties in measurement" (2008)

Description

Several datasets found in "Annex H" of the GUM that are used in illustrating the different approaches to quantifying measurement uncertainty.

Details

H.2: Simultaneous resistance and reactance measurement, Table H.2

This example demonstrates the treatment of multiple measurands or output quantities determined simultaneously in the same measurement and the correlation of their estimates. It considers only the random variations of the observations; in actual practice, the uncertainties of corrections for systematic effects would also contribute to the uncertainty of the measurement results. The data are analysed in two different ways with each yielding essentially the same numerical values.

H.2.1 The measurement problem:

The resistance R and the reactance X of a circuit element are determined by measuring the amplitude V of a sinusoidally-alternating potential difference across its terminals, the amplitude I of the alternating current passing through it, and the phase-shift angle ϕ of the alternating potential difference relative to the alternating current. Thus the three input quantities are V , I , and ϕ and the three output quantities -the measurands- are the three impedance components R , X , and Z . Since $Z^2 = R^2 + X^2$, there are only two independent output quantities.

H.2.2 Mathematical model and data:

The measurands are related to the input quantities by Ohm's law:

$$R = \frac{V}{I} \cos \phi; \quad X = \frac{V}{I} \sin \phi; \quad Z = \frac{V}{I} \quad (\text{H.7})$$

H.3: Calibration of a thermometer, Table H.6

This example illustrates the use of the method of least squares to obtain a linear calibration curve and how the parameters of the fit, the intercept and slope, and their estimated variances and covariance, are used to obtain from the curve the value and standard uncertainty of a predicted correction.

H.3.1 The measurement problem:

A thermometer is calibrated by comparing $n = 11$ temperature readings t_k of the thermometer, each having negligible uncertainty, with corresponding known reference temperatures $t_{R,k}$ in the temperature range 21°C to 27°C to obtain the corrections $b_k = t_{R,k} - t_k$ to the readings. The *measured* corrections b_k and *measured* temperatures t_k are the input quantities of the evaluation. A linear calibration curve

$$b(t) = y_1 + y_2(t - t_0) \quad (\text{H.12})$$

is fitted to the measured corrections and temperatures by the method of least squares. The parameters y_1 and y_2 , which are respectively the intercept and slope of the calibration curve, are the two measurands or output quantities to be determined. The temperature t_0 is a conveniently chosen exact reference temperature; it is not an independent parameter to be determined by the least-squares fit. Once y_1 and y_2 are found, along with their estimated variances and covariance, Equation (H.12)

can be used to predict the value and standard uncertainty of the correction to be applied to the thermometer for any value t of the temperature.

H.4: Measurement of activity, Table H.7

This example is similar to example H.2, the simultaneous measurement of resistance and reactance, in that the data can be analysed in two different ways but each yields essentially the same numerical result. The first approach illustrates once again the need to take the observed correlations between input quantities into account.

H.4.1 The measurement problem:

The unknown radon (^{222}Rn) activity concentration in a water sample is determined by liquid-scintillation counting against a radon-in-water standard sample having a known activity concentration. The unknown activity concentration is obtained by measuring three counting sources consisting of approximately 5g of water and 12g of organic emulsion scintillator in vials of volume 22ml:

Source (a) a *standard* consisting of a mass m_S of the standard solution with a known activity concentration;

Source (b) a matched *blank* water sample containing no radioactive material, used to obtain the background counting rate;

Source (c) the *sample* consisting of an aliquot of mass m_x with unknown activity concentration.

Six cycles of measurement of the three counting sources are made in the order standard - blank - sample; and each dead-time-corrected counting interval T_0 for each source during all six cycles is 60 minutes. Although the background counting rate cannot be assumed to be constant over the entire counting interval (65 hours), it is assumed that the number of counts obtained for each blank may be used as representative of the background counting rate during the measurements of the standard and sample in the same cycle. The data are given in Table H.7, where

t_S, t_B, t_x are the times from the reference time $t = 0$ to the midpoint of the dead-time-corrected counting intervals $T_0 = 60$ min for the standard, blank, and sample vials, respectively; although t_B is given for completeness, it is not needed in the analysis;

C_S, C_B, C_x are the number of counts recorded in the dead-time-corrected counting intervals $T_0 = 60$ min for the standard, blank, and sample vials, respectively.

The observed counts may be expressed as

$$C_S = C_B + \varepsilon A_S T_0 m_S e^{-\lambda t_S} \quad (\text{H.18a})$$

$$C_x = C_B + \varepsilon A_x T_0 m_x e^{-\lambda t_x} \quad (\text{H.18b})$$

where

ε is the liquid scintillation detection efficiency for ^{222}Rn for a given source composition, assumed to be independent of the activity level;

A_S is the activity concentration of the standard at the reference time $t = 0$;

A_x is the measurand and is defined as the unknown activity concentration of the sample at the reference time $t = 0$;

m_S is the mass of the standard solution;

m_x is the mass of the sample aliquot;

λ is the decay constant for ^{222}Rn : $\lambda = (\ln 2)/T_{1/2} = 1.25894 \cdot 10^{-4} \text{ min}^{-1}$ ($T_{1/2} = 5505.8 \text{ min}$).

(...) This suggests combining Equations (H.18a) and (H.18b) to obtain the following expression for the unknown concentration in terms of the known quantities:

$$\dots = A_S \frac{m_S}{m_x} \frac{C_x - C_B}{C_S - C_B} e^{\lambda(t_x - t_S)} \quad (\text{H.19})$$

where $(C_x - C_B)e^{\lambda t_x}$ and $(C_S - C_B)e^{\lambda t_S}$ are, respectively, the background-corrected counts of the sample and the standard at the reference time $t = 0$ and for the time interval $T_0 = 60$ min.

Author(s)

Andrej-Nikolai Spiess, taken mainly from the GUM 2008 manual.

References

Evaluation of measurement data - Guide to the expression of uncertainty in measurement. JCGM 100:2008 (GUM 1995 with minor corrections).

https://www.bipm.org/documents/20126/2071204/JCGM_100_2008_E.pdf.

Evaluation of measurement data - Supplement 1 to the Guide to the expression of uncertainty in measurement - Propagation of distributions using a Monte Carlo Method.

JCGM 101:2008.

https://www.bipm.org/documents/20126/2071204/JCGM_101_2008_E.pdf/325dcaad-c15a-407c-1105-8b7f322d65

Examples

```
## See "Examples" in 'propagate'.
```

fitDistr

Fitting distributions to observations/Monte Carlo simulations

Description

This function fits 35 different continuous distributions by (weighted) NLS to the histogram of Monte Carlo simulation results as obtained by [propagate](#) or any other vector containing large-scale observations. Finally, the fits are sorted by ascending [BIC](#).

Usage

```
fitDistr(object, nbin = 100, weights = FALSE, verbose = TRUE,
         brute = c("fast", "slow"), plot = c("hist", "qq", "none"), distsel = NULL, ...)
```

Arguments

object	an object of class 'propagate' or a vector containing observations.
nbin	the number of bins in the histogram.
weights	numeric or logical. Either a numeric vector of weights, or if TRUE, the distributions are fitted with $\text{weights} = 1/(\text{counts per bin})$.
verbose	logical. If TRUE, steps of the analysis are printed to the console.
brute	complexity of the brute force approach. See 'Details'.
plot	if "hist", a plot with the "best" distribution (in terms of lowest BIC) on top of the histogram is displayed. If "qq", a QQ-Plot will display the difference between the observed and fitted quantiles.

distsel a vector of distribution numbers to select from the complete cohort as listed below, e.g. c(1:10, 15).

... other parameters to be passed to the plots.

Details

Fits the following 35 distributions using (weighted) residual sum-of-squares as the minimization criterion for `minpack.lm::nls.lm`:

- 1) Normal distribution (`dnorm`) => https://en.wikipedia.org/wiki/Normal_distribution
- 2) Skewed-normal distribution (`propagate::dsn`) => https://en.wikipedia.org/wiki/Skew_normal_distribution
- 3) Generalized normal distribution (`propagate::dgnorm`) => https://en.wikipedia.org/wiki/Generalized_normal_distribution
- 4) Log-normal distribution (`dlnorm`) => https://en.wikipedia.org/wiki/Log-normal_distribution
- 5) Scaled and shifted t-distribution (`propagate::dst`) => GUM 2008, Chapter 6.4.9.2.
- 6) Logistic distribution (`dlogis`) => https://en.wikipedia.org/wiki/Logistic_distribution
- 7) Uniform distribution (`dunif`) => [https://en.wikipedia.org/wiki/Uniform_distribution_\(continuous\)](https://en.wikipedia.org/wiki/Uniform_distribution_(continuous))
- 8) Triangular distribution (`propagate::dtriang`) => https://en.wikipedia.org/wiki/Triangular_distribution
- 9) Trapezoidal distribution (`propagate::dtrap`) => https://en.wikipedia.org/wiki/Trapezoidal_distribution
- 10) Curvilinear Trapezoidal distribution (`propagate::dctrap`) => GUM 2008, Chapter 6.4.3.1
- 11) Gamma distribution (`dgamma`) => https://en.wikipedia.org/wiki/Gamma_distribution
- 12) Inverse Gamma distribution (`propagate::dinvgamma`) => https://en.wikipedia.org/wiki/Inverse-gamma_distribution
- 13) Cauchy distribution (`dcauchy`) => https://en.wikipedia.org/wiki/Cauchy_distribution
- 14) Laplace distribution (`propagate::dlaplace`) => https://en.wikipedia.org/wiki/Laplace_distribution
- 15) Gumbel distribution (`propagate::dgumbel`) => https://en.wikipedia.org/wiki/Gumbel_distribution
- 16) Johnson SU distribution (`propagate::dJSU`) => https://en.wikipedia.org/wiki/Johnson_SU_distribution
- 17) Johnson SB distribution (`propagate::dJSB`) => https://variation.com/wp-content/distribution_analyzer_help/hs126.htm
- 18) Three-parameter Weibull distribution (`propagate::dweibull2`) => https://en.wikipedia.org/wiki/Weibull_distribution
- 19) Two-parameter beta distribution (`dbeta2`) => https://en.wikipedia.org/wiki/Beta_distribution#Two_parameters_2
- 20) Four-parameter beta distribution (`propagate::dbeta2`) => https://en.wikipedia.org/wiki/Beta_distribution#Four_parameters_2
- 21) Arcsine distribution (`propagate::darcsin`) => https://en.wikipedia.org/wiki/Arcsine_distribution
- 22) Von Mises distribution (`propagate::dmises`) => https://en.wikipedia.org/wiki/Von_Mises_distribution
- 23) Inverse Gaussian distribution (`propagate::dinvgauss`) => https://en.wikipedia.org/wiki/Inverse_Gaussian_distribution
- 24) Generalized Extreme Value distribution (`propagate::dgevd`) => https://en.wikipedia.org/wiki/Generalized_extreme_value_distribution

- org/wiki/Generalized_extreme_value_distribution
- 25) Rayleigh distribution (propagate:::drayleigh) => https://en.wikipedia.org/wiki/Rayleigh_distribution
- 26) Chi-square distribution (dchisq) => https://en.wikipedia.org/wiki/Chi-squared_distribution
- 27) Exponential distribution (dexp) => https://en.wikipedia.org/wiki/Exponential_distribution
- 28) F-distribution (df) => <https://en.wikipedia.org/wiki/F-distribution>
- 29) Burr distribution (dburr) => https://en.wikipedia.org/wiki/Burr_distribution
- 30) Chi distribution (dchi) => https://en.wikipedia.org/wiki/Chi_distribution
- 31) Inverse Chi-square distribution (dinvchisq) => https://en.wikipedia.org/wiki/Inverse-chi-squared_distribution
- 32) Cosine distribution (dcosine) => https://en.wikipedia.org/wiki/Raised_cosine_distribution
- 33) Pareto distribution (dpareto) => https://en.wikipedia.org/wiki/Pareto_distribution
- 34) Levy distribution (dLevy) => https://en.wikipedia.org/wiki/Levy_distribution
- 35) Gompertz distribution (dgomperztz) => https://en.wikipedia.org/wiki/Gompertz_distribution

All distributions are fitted with a brute force approach, in which the parameter space is extended over three orders of magnitude $(0.1, 1, 10) \times \beta_i$ when brute = "fast", or five orders $(0.01, 0.1, 1, 10, 100) \times \beta_i$ when brute = "slow". Approx. 20-90s are needed to fit for the fast version, depending mainly on the number of bins.

The goodness-of-fit (GOF) is calculated with BIC from the (weighted) log-likelihood of the fit:

$$\ln(L) = 0.5 \cdot \left(-N \cdot \left(\ln(2\pi) + 1 + \ln(N) - \sum_{i=1}^n \log(w_i) + \ln \left(\sum_{i=1}^n w_i \cdot x_i^2 \right) \right) \right)$$

$$\text{BIC} = -2\ln(L) + (N - k)\ln(N)$$

with x_i = the residuals from the NLS fit, N = the length of the residual vector, k = the number of parameters of the fitted model and w_i = the weights.

In contrast to some other distribution fitting softwares (i.e. Easyfit, Mathwave) that use residual sum-of-squares/Anderson-Darling/Kolmogorov-Smirnov statistics as GOF measures, the application of BIC accounts for increasing number of parameters in the distribution fit and therefore compensates for overfitting. Hence, this approach is more similar to ModelRisk (Vose Software) and as employed in fitdistr of the 'MASS' package. Another application is to identify a possible distribution for the raw data prior to using Monte Carlo simulations from this distribution. However, a decent number of observations should be at hand in order to obtain a realistic estimate of the proper distribution. See 'Examples'.

The code for the density functions can be found in file "distr-densities.R".

IMPORTANT: It can be feasible to set weights = TRUE in order to give more weight to bins with low counts. See 'Examples'. ALSO: Distribution fitting is highly sensitive to the number of defined histogram bins, so it is advisable to change this parameter and inspect if the order of fitted distributions remains stable.

Value

A list with the following items:

stat: the by BIC value ascendingly sorted distribution names, including RSS and MSE.

fit: a list of the results from minpack.lm:::nls.lm for each distribution model, also sorted ascendingly by BIC values.

par: a list of the estimated parameters of the models in fit.
 se: a list of the parameters' standard errors, calculated from the square root of the covariance matrices diagonals.
 dens: a list with all density function used for fitting, sorted as in fit.
 bestfit: the best model in terms of lowest BIC.
 bestpar: the parameters of bestfit.
 bestse: the parameters' standard errors of bestfit.
 fitted: the fitted values of bestfit.
 residuals: the residuals of bestfit.

Author(s)

Andrej-Nikolai Spiess

References

Continuous univariate distributions, Volume 1.
 Johnson NL, Kotz S and Balakrishnan N.
Wiley Series in Probability and Statistics, 2.ed (2004).
 Univariate distribution relationships.
 Leemis LM and McQueston JT.
The American Statistician (2008), **62**: 45-53.

Examples

```

## Linear example, small error
## => Normal distribution.
## Don't set 'distsel' for full test
EXPR1 <- expression(x + y)
x <- c(5, 0.1)
y <- c(1, 0.01)
DF1 <- cbind(x, y)
RES1 <- propagate(expr = EXPR1, data = DF1, type = "stat",
                 nsim = 100000, check = FALSE)
fitDistr(RES1, nbin = 200, distsel = 1:10)

```

interval

Uncertainty propagation based on interval arithmetics

Description

Calculates the uncertainty of a model by using interval arithmetics based on a "combinatorial sequence grid evaluation" approach, thereby avoiding the classical dependency problem that inflates the result interval.

Usage

```
interval(df, expr, seq = 10, plot = TRUE)
```

Arguments

df	a 2-row dataframe/matrix with lower border values A_i in the first row and upper border values B_i in the second row. Column names must correspond to the variable names in expr.
expr	an expression, such as expression(x/y).
seq	the sequence length from A_i to B_i in $[A_i, B_i]$.
plot	logical. If TRUE, plots the evaluations and min/max values as blue border lines.

Details

For two variables x, y with intervals $[x_1, x_2]$ and $[y_1, y_2]$, the four basic arithmetic operations $\langle \text{op} \rangle \in \{+, -, \cdot, /\}$ are

$$[x_1, x_2] \langle \text{op} \rangle [y_1, y_2] = [\min(x_1 \langle \text{op} \rangle y_1, x_1 \langle \text{op} \rangle y_2, x_2 \langle \text{op} \rangle y_1, x_2 \langle \text{op} \rangle y_2), \max(x_1 \langle \text{op} \rangle y_1, x_1 \langle \text{op} \rangle y_2, x_2 \langle \text{op} \rangle y_1, x_2 \langle \text{op} \rangle y_2)]$$

So for a function $f([x_1, x_2], [y_1, y_2], [z_1, z_2], \dots)$ with k variables, we have to create all combinations $C_i = (\{\{x_1, x_2\}, \{y_1, y_2\}, \{z_1, z_2\}, \dots\})$, evaluate their function values $R_i = f(C_i)$ and select $R = [\min R_i, \max R_i]$.

The so-called *dependency problem* is a major obstacle to the application of interval arithmetic and arises when the same variable exists in several terms of a complicated and often nonlinear function. In these cases, over-estimation can cover a range that is significantly larger, i.e. $\min R_i \ll \min f(x, y, z, \dots), \max R_i \gg \max f(x, y, z, \dots)$. For an example, see https://en.wikipedia.org/w/index.php?title=Interval_arithmetic under "Dependency problem". A partial solution to this problem is to refine R_i by dividing $[x_1, x_2]$ into i smaller subranges to obtain sequence $(x_1, x_{1.1}, x_{1.2}, \dots, x_{1.i}, x_2)$. Again, all combinations are evaluated as described above, resulting in a larger number of R_i in which $\min R_i$ and $\max R_i$ may be closer to $\min f(x, y, z, \dots)$ and $\max f(x, y, z, \dots)$, respectively. This is the "combinatorial sequence grid evaluation" approach which works quite well in scenarios where monotonicity changes direction (see 'Examples'), obviating the need to create multivariate derivatives (Hessians) or use some multivariate minimization algorithm.

If intervals are of type $[x_1 < 0, x_2 > 0]$, a zero is included into the middle of the sequence to avoid wrong results in case of even powers, i.e. $[-1, 1]^2 = [-1, 1][-1, 1] = [-1, 1]$ when actually the right interval is $[0, 1]$, see `curve(x^2, -1, 1)`.

Value

A 2-element vector with the resulting interval and an (optional) plot of all evaluations.

Author(s)

Andrej-Nikolai Spiess

References

Wikipedia entry is quite good, especially the section on the 'dependency problem':
https://en.wikipedia.org/w/index.php?title=Interval_arithmetic

Comparison to Monte Carlo and error propagation:
 Interval Arithmetic in Power Flow Analysis.

Wang Z & Alvarado FL.
Power Industry Computer Application Conference (1991): 156-162.

Computer implementation

Interval arithmetic: From principles to implementation.

Hickey T, Ju Q, Van Emden MH.

JACM (2001), **48**: 1038-1068.

Complete Interval Arithmetic and its Implementation on the Computer.

Kulisch UW.

In: Numerical Validation in Current Hardware Architectures. Lecture Notes in Computer Science **5492** (2009): 7-26.

Examples

```
## Example 1: even squaring of negative interval.
EXPR1 <- expression(x^2)
DAT1 <- data.frame(x = c(-1, 1))
interval(DAT1, EXPR1)

## Example 2: A complicated nonlinear model.
## Reduce sequence length to 2 => original interval
## for quicker evaluation.
EXPR2 <- expression(C * sqrt((520 * H * P)/(M *(t + 460))))
H <- c(64, 65)
M <- c(16, 16.2)
P <- c(361, 365)
t <- c(165, 170)
C <- c(38.4, 38.5)
DAT2 <- makeDat(EXPR2)
interval(DAT2, EXPR2, seq = 2)

## Example 3: Body Mass Index taken from
## http://en.wikipedia.org/w/index.php?title=Interval_arithmetic
EXPR3 <- expression(m/h^2)
m <- c(79.5, 80.5)
h <- c(1.795, 1.805)
DAT3 <- makeDat(EXPR3)
interval(DAT3, EXPR3)

## Example 4: Linear model.
EXPR4 <- expression(a * x + b)
a <- c(1, 2)
b <- c(5, 7)
x <- c(2, 3)
DAT4 <- makeDat(EXPR4)
interval(DAT4, EXPR4)

## Example 5: Overestimation from dependency problem.
# Original interval with seq = 2 => [1, 7]
EXPR5 <- expression(x^2 - x + 1)
x <- c(-2, 1)
DAT5 <- makeDat(EXPR5)
```

```
interval(DAT5, EXPR5, seq = 2)

# Refine with large sequence => [0.75, 7]
interval(DAT5, EXPR5, seq = 100)
# Tallies with curve function.
curve(x^2 - x + 1, -2, 1)

## Example 6: Underestimation from dependency problem.
# Original interval with seq = 2 => [0, 0]
EXPR6 <- expression(x - x^2)
x <- c(0, 1)
DAT6 <- makeDat(EXPR6)
interval(DAT6, EXPR6, seq = 2)

# Refine with large sequence => [0, 0.25]
interval(DAT6, EXPR6, seq = 100)
# Tallies with curve function.
curve(x - x^2, 0, 1)
```

makeDat

Create a dataframe from the variables defined in an expression

Description

Creates a dataframe from the variables defined in an expression by [cbinding](#) the corresponding data found in the workspace. This is a convenience function for creating a dataframe to be passed to [propagate](#), when starting with data which was simulated from distributions, i.e. when `type = "sim"`. Will throw an error if a variable is defined in the expression but is not available from the workspace.

Usage

```
makeDat(expr)
```

Arguments

`expr` an expression to be use for [propagate](#).

Value

A dataframe containing the data defined in `expr` in columns.

Author(s)

Andrej-Nikolai Spiess

Examples

```
## Simulating from uniform
## and normal distribution,
## run 'propagate'.
EXPR1 <- expression(a + b^c)
a <- rnorm(100000, 12, 1)
b <- rnorm(100000, 5, 0.1)
c <- runif(100000, 6, 7)

DAT1 <- makeDat(EXPR1)
propagate(EXPR1, DAT1, type = "sim", cov = "diag")
```

makeDerivs

Utility functions for creating Gradient- and Hessian-like matrices with symbolic derivatives and evaluating them in an environment

Description

These are three different utility functions that create matrices containing the symbolic partial derivatives of first (`makeGrad`) and second (`makeHess`) order and a function for evaluating these matrices in an environment. The evaluations of the symbolic derivatives are used within the `propagate` function to calculate the propagated uncertainty, but these functions may also be useful for other applications.

Usage

```
makeGrad(expr, order = NULL)
makeHess(expr, order = NULL)
evalDerivs(deriv, envir)
```

Arguments

<code>expr</code>	an expression, such as <code>expression(x/y)</code> .
<code>order</code>	order of creating partial derivatives, i.e. <code>c(2, 1)</code> . See 'Examples'.
<code>deriv</code>	a matrix returned from <code>makeGrad</code> or <code>makeHess</code> .
<code>envir</code>	an environment to evaluate in. By default the workspace.

Details

Given a function $f(x_1, x_2, \dots, x_n)$, the following matrices containing symbolic derivatives of f are returned:

makeGrad:

$$\nabla(f) = \left[\frac{\partial f}{\partial x_1}, \dots, \frac{\partial f}{\partial x_n} \right]$$

makeHess:

$$H(f) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_1 \partial x_n} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \cdots & \frac{\partial^2 f}{\partial x_2 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1} & \frac{\partial^2 f}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f}{\partial x_n^2} \end{bmatrix}$$

Value

The symbolic or evaluated Gradient/Hessian matrices.

Author(s)

Andrej-Nikolai Spiess

References

The Matrix Cookbook (Version November 2012).

Petersen KB & Pedersen MS.

<http://ais.informatik.uni-freiburg.de/teaching/ws12/mapping/pdf/imm3274.pdf>

Examples

```

EXPR <- expression(a^b + sin(c))
ENVIR <- list(a = 2, b = 3, c = 4)

## First-order partial derivatives: Gradient.
GRAD <- makeGrad(EXPR)

## This will evaluate the Gradient.
evalDerivs(GRAD, ENVIR)

## Second-order partial derivatives: Hessian.
HESS <- makeHess(EXPR)

## This will evaluate the Hessian.
evalDerivs(HESS, ENVIR)

## Change derivatives order.
GRAD <- makeGrad(EXPR, order = c(2,1,3))
evalDerivs(GRAD, ENVIR)

```

`matrixStats`*Fast column- and row-wise versions of variance coded in C++*

Description

These two functions are fast C++ versions for column- and row-wise [variance](#) calculation on matrices/data.frames and are meant to substitute the classical `apply(mat, 1, var)` approach.

Usage

```
colVarsC(x)
rowVarsC(x)
```

Arguments

`x` a matrix or data.frame

Details

They are coded in a way that they automatically remove NA values, so they behave like `na.rm = TRUE`.

Value

A vector with the variance values.

Author(s)

Andrej-Nikolai Spiess

Examples

```
## Speed comparison on large matrix.
## ~ 110x speed increase!
## Not run:
MAT <- matrix(rnorm(10 * 500000), ncol = 10)
system.time(RES1 <- apply(MAT, 1, var))
system.time(RES2 <- rowVarsC(MAT))
all.equal(RES1, RES2)

## End(Not run)
```

mixCov	<i>Aggregating covariances matrices and/or error vectors into a single covariance matrix</i>
--------	--

Description

This function aggregates covariances matrices, single variance values or a vector of multiple variance values into one final covariance matrix suitable for [propagate](#).

Usage

```
mixCov(...)
```

Arguments

... either covariance matrices, or a vector of single/multiple variance values.

Details

'Mixes' (aggregates) data of the following types into a final covariance matrix:

- 1) covariance matrices Σ that are already available.
- 2) single variance values σ^2 .
- 3) a vector of variance values $\sigma_1^2, \sigma_2^2, \dots, \sigma_n^2$.

This is accomplished by filling a $m_1 + m_2 + \dots + m_n$ sized square matrix \mathbf{C} successively with elements $1 \dots m_1, m_1 + 1 \dots m_1 + m_2, \dots, m_n + 1 \dots m_n + m_{n+1}$ with either covariance matrices at $C_{m_n+1 \dots m_n+m_{n+1}, m_n+1 \dots m_n+m_{n+1}}$ or single variance values on the diagonals at C_{m_n, m_n} .

Value

The aggregated covariance matrix.

Author(s)

Andrej-Nikolai Spiess

References

Evaluation of measurement data - Guide to the expression of uncertainty in measurement.
JCGM 100:2008 (GUM 1995 with minor corrections).
https://www.bipm.org/documents/20126/2071204/JCGM_100_2008_E.pdf/.

Evaluation of measurement data - Supplement 1 to the Guide to the expression of uncertainty in measurement - Propagation of distributions using a Monte Carlo Method.
JCGM 101:2008.
https://www.bipm.org/documents/20126/2071204/JCGM_100_2008_E.pdf/.

Examples

```
#####
## Example in Annex H.4.1 from the GUM 2008 manual
## (see 'References'), measurement of activity.
## This will give exactly the same values as Table H.8.
data(H.4)
attach(H.4)
T0 <- 60
lambda <- 1.25894E-4
Rx <- ((Cx - Cb)/60) * exp(lambda * tx)
Rs <- ((Cs - Cb)/60) * exp(lambda * ts)

mRx <- mean(Rx)
sRx <- sd(Rx)/sqrt(6)
mRx
sRx

mRs <- mean(Rs)
sRs <- sd(Rs)/sqrt(6)
mRs
sRs

R <- Rx/Rs
mR <- mean(R)
sR <- sd(R)/sqrt(6)
mR
sR

cor(Rx, Rs)

## Definition as in H.4.3.
As <- c(0.1368, 0.0018)
ms <- c(5.0192, 0.005)
mx <- c(5.0571, 0.001)

## We have to scale Rs/Rx by sqrt(6) to get the
## corresponding covariances.
Rs <- Rs/sqrt(6)
Rx <- Rx/sqrt(6)

## Here we create an aggregated covariance matrix
## from the raw and summary data.
COV1 <- cov(cbind(Rs, Rx))
COV <- mixCov(COV1, As[2]^2, ms[2]^2, mx[2]^2)
COV

## Prepare the data for 'propagate'.
MEANS <- c(mRs, mRx, As[1], ms[1], mx[1])
SDS <- c(sRs, sRx, As[2], ms[2], mx[2])
DAT <- rbind(MEANS, SDS)
colnames(DAT) <- c("Rs", "Rx", "As", "ms", "mx")
```

```
## This will give exactly the same values as
## in H.4.3/H.4.3.1.
EXPR <- expression(As * (ms/mx) * (Rx/Rs))
propagate(EXPR, data = DAT, cov = COV, nsim = 10000, check = FALSE)
```

moments

*Skewness and (excess) Kurtosis of a vector of values***Description**

These functions calculate skewness and excess kurtosis of a vector of values. They were taken from the package 'moments'.

Usage

```
skewness(x, na.rm = FALSE)
kurtosis(x, na.rm = FALSE)
```

Arguments

x a numeric vector, matrix or data frame.
na.rm logical. Should missing values be removed?

Details

Skewness:

$$\frac{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^3}{\left(\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2\right)^{3/2}}$$

(excess) Kurtosis:

$$\frac{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^4}{\left(\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2\right)^2} - 3$$

Value

The skewness/kurtosis values.

Author(s)

Andrej-Nikolai Spiess

Examples

```
X <- rnorm(100, 20, 2)
skewness(X)
kurtosis(X)
```

numDerivs	<i>Functions for creating Gradient and Hessian matrices by numerical differentiation (Richardson's method) of the partial derivatives</i>
-----------	---

Description

These two functions create Gradient and Hessian matrices by Richardson's central finite difference method of the partial derivatives for any expression.

Usage

```
numGrad(expr, envir = .GlobalEnv)
numHess(expr, envir = .GlobalEnv)
```

Arguments

expr an expression, such as expression(x/y).
 envir the `environment` to evaluate in.

Details

Calculates first- and second-order numerical approximation using Richardson's **central difference formula**:

$$f'_i(x) \approx \frac{f(x_1, \dots, x_i + d, \dots, x_n) - f(x_1, \dots, x_i - d, \dots, x_n)}{2d}$$

$$f''_i(x) \approx \frac{f(x_1, \dots, x_i + d, \dots, x_n) - 2f(x_1, \dots, x_n) + f(x_1, \dots, x_i - d, \dots, x_n)}{d^2}$$

Value

The numeric Gradient/Hessian matrices.

Note

The two functions are modified versions of the `genD` function in the 'numDeriv' package, but a bit more easy to handle because they use expressions and the function's `x` value must not be defined as splitted scalar values `x[1]`, `x[2]`, ... `x[n]` in the body of the function.

Author(s)

Andrej-Nikolai Spiess

Examples

```
## Check for equality of symbolic
## and numerical derivatives.
EXPR <- expression(2^x + sin(2 * y) - cos(z))
x <- 5
y <- 10
z <- 20

symGRAD <- evalDerivs(makeGrad(EXPR))
numGRAD <- numGrad(EXPR)
all.equal(symGRAD, numGRAD)

symHESS <- evalDerivs(makeHess(EXPR))
numHESS <- numHess(EXPR)
all.equal(symHESS, numHESS)
```

plot.propagate *Plotting function for 'propagate' objects*

Description

Creates a histogram (blue) of the evaluated results from the multivariate simulated data, along with a density curve (red), α -based confidence intervals (GUM: dashed black; MC: solid black), median (orange) and mean (green).

Usage

```
## S3 method for class 'propagate'
plot(x, logx = FALSE, breaks = 100, ...)
```

Arguments

x	an object returned from propagate .
logx	logical. Should the data be displayed on a logarithmic abscissa?
breaks	numeric. The number of bins for the histogram.
...	other parameters to hist .

Value

A plot as described above.

Author(s)

Andrej-Nikolai Spiess

Examples

```

EXPR1 <- expression(x^2 * sin(y))
x <- c(5, 0.01)
y <- c(1, 0.01)
DF1 <- cbind(x, y)
RES1 <- propagate(expr = EXPR1, data = DF1, type = "stat",
                 nsim = 100000, alpha = 0.01)
plot(RES1)

```

predictNLS

Confidence/prediction intervals for (weighted) nonlinear models based on uncertainty propagation

Description

A function for calculating confidence/prediction intervals of (weighted) nonlinear models for the supplied or new predictor values, by using first-/second-order Taylor expansion and Monte Carlo simulation. This approach can be used to construct more realistic error estimates and confidence/prediction intervals for nonlinear models than what is possible with only a simple linearization (first-order Taylor expansion) approach. Another application is when there is an "error in x" setup with uncertainties in the predictor variable (See 'Examples'). This function will also work in the presence of multiple predictors with/without errors.

Usage

```

predictNLS(model, newdata, newerror, interval = c("confidence", "prediction", "none"),
           alpha = 0.05, ...)

```

Arguments

model	a model obtained from nls or nlsLM (package 'minpack.lm').
newdata	a data frame with new predictor values, having the same column names as in model. See predict.nls and 'Examples'. If omitted, the model's predictor values are employed.
newerror	a data frame with optional error values, having the same column names as in model and in the same order as in newdata. See 'Examples'.
interval	A character string indicating if confidence/prediction intervals are to be calculated or not.
alpha	the α level.
...	other parameters to be supplied to propagate .

Details

Calculation of the propagated uncertainty σ_y using $\nabla\Sigma\nabla^T$ is called the "Delta Method" and is widely applied in NLS fitting. However, this method is based on first-order Taylor expansion and thus assumes linearity around $f(x)$. The second-order approach as implemented in the `propagate` function can partially correct for this restriction by using a second-order polynomial around $f(x)$. Confidence and prediction intervals are calculated in a usual way using $t(1 - \frac{\alpha}{2}, \nu) \cdot \sigma_y$ (1) or $t(1 - \frac{\alpha}{2}, \nu) \cdot \sqrt{\sigma_y^2 + \sigma_r^2}$ (2), respectively, where the residual variance $\sigma_r^2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n - \nu}$ (3). The inclusion of σ_r^2 in the prediction interval is implemented as an extended gradient and "augmented" covariance matrix. So instead of using $y = f(x, \beta)$ (4) we take $y = f(x, \beta) + \sigma_r^2$ (5) as the expression and augment the $n \times n$ covariance matrix C to an $(n + 1) \times (n + 1)$ covariance matrix, where $C_{n+1, n+1} = \sigma_r^2$. Partial differentiation and matrix multiplication will then yield, for example with two coefficients β_1 and β_2 and their corresponding covariance matrix Σ :

$$\begin{bmatrix} \frac{\partial f}{\partial \beta_1} & \frac{\partial f}{\partial \beta_2} & \mathbf{1} \end{bmatrix} \begin{bmatrix} \sigma_1^2 & \sigma_1\sigma_2 & 0 \\ \sigma_2\sigma_1 & \sigma_2^2 & 0 \\ 0 & 0 & \sigma_r^2 \end{bmatrix} \begin{bmatrix} \frac{\partial f}{\partial \beta_1} \\ \frac{\partial f}{\partial \beta_2} \\ \mathbf{1} \end{bmatrix} = \left(\frac{\partial f}{\partial \beta_1}\right)^2 \sigma_1^2 + 2 \frac{\partial f}{\partial \beta_1} \frac{\partial f}{\partial \beta_2} \sigma_1\sigma_2 + \left(\frac{\partial f}{\partial \beta_2}\right)^2 \sigma_2^2 + \sigma_r^2$$

$\equiv \sigma_y^2 + \sigma_r^2$, where $\sigma_y^2 + \sigma_r^2$ then goes into (2).

The advantage of the augmented covariance matrix is that it can be exploited for creating Monte Carlo simulation-based prediction intervals. It is based on the paradigm that we simply add another dimension with $\mu = 0$ and $\sigma^2 = \sigma_r^2$ to the MC random number generator (the Gaussian Copula with t -margins). All n simulations are then evaluated with (5) and the usual $[1 - \frac{\alpha}{2}, \frac{\alpha}{2}]$ quantiles calculated.

If errors are supplied to the predictor values in `newerror`, they need to have the same column names and order than the new predictor values.

Value

A list with the following items:

summary: The mean/error estimates obtained from first-/second-order Taylor expansion and Monte Carlo simulation, together with calculated confidence/prediction intervals based on asymptotic normality.

prop: the complete output from `propagate` for each value in `newdata`.

Author(s)

Andrej-Nikolai Spiess

References

Nonlinear Regression.

Seber GAF & Wild CJ.

John Wiley & Sons; 1ed, 2003.

Nonlinear Regression Analysis and its Applications.

Bates DM & Watts DG.

Wiley-Interscience; 1ed, 2007.

Statistical Error Propagation.

Tellinghuisen J.

J. Phys. Chem. A (2001), **47**: 3917-3921.

Least-squares analysis of data with uncertainty in x and y: A Monte Carlo methods comparison.

Tellinghuisen J.

Chemometr Intell Lab (2010), **47**: 160-169.

From the author's blog:

<http://rmazing.wordpress.com/2013/08/14/predictnls-part-1-monte-carlo-simulation-confidence-intervals-for-nls-models/>

<http://rmazing.wordpress.com/2013/08/26/predictnls-part-2-taylor-approximation-confidence-intervals-for-nls-models/>

Examples

```
## In these examples, 'nsim = 100000' to save
## Rcmd check time (CRAN). It is advocated
## to use at least 'nsim = 100000' though...

## Example from ?nls.
DNase1 <- subset(DNase, Run == 1)
fm3DNase1 <- nls(density ~ Asym/(1 + exp((xmid - log(conc))/scal)),
                data = DNase1, start = list(Asym = 3, xmid = 0, scal = 1))

## Using a single predictor value without error.
PROP1 <- predictNLS(fm3DNase1, newdata = data.frame(conc = 2), nsim = 10000)
PRED1 <- predict(fm3DNase1, newdata = data.frame(conc = 2))
PROP1$summary
PRED1
## => Prop.Mean.1 equal to PRED1

## Using a single predictor value with error.
PROP2 <- predictNLS(fm3DNase1, newdata = data.frame(conc = 2),
                   newerror = data.frame(conc = 0.5), nsim = 10000)
PROP2$summary

## Using a sequence of predictor values without error.
CONC <- seq(1, 12, by = 1)
PROP3 <- predictNLS(fm3DNase1, newdata = data.frame(conc = CONC), nsim = 10000)
PRED3 <- predict(fm3DNase1, newdata = data.frame(conc = CONC))
PROP3$summary
PRED3
## => Prop.Mean.1 equal to PRED3

## Plot mean and confidence values from first-/second-order
## Taylor expansion and Monte Carlo simulation.
plot(DNase1$conc, DNase1$density)
lines(DNase1$conc, fitted(fm3DNase1), lwd = 2, col = 1)
points(CONC, PROP3$summary[, 1], col = 2, pch = 16)
lines(CONC, PROP3$summary[, 5], col = 2)
lines(CONC, PROP3$summary[, 6], col = 2)
```

```
lines(CONC, PROP3$summary[, 11], col = 4)
lines(CONC, PROP3$summary[, 12], col = 4)
```

propagate	<i>Propagation of uncertainty using higher-order Taylor expansion and Monte Carlo simulation</i>
-----------	--

Description

A general function for the calculation of uncertainty propagation by first-/second-order Taylor expansion and Monte Carlo (MC) simulation including covariances. Input data can be any symbolic/numeric differentiable expression and data based on summaries (Mean/SEM/DOF), experimental measurements or sampled from distributions. Uncertainty propagation is based completely on matrix calculus accounting for full covariance structure. Monte Carlo simulation is conducted using a Gaussian copula with marginal t -distributions. Propagation confidence intervals are calculated from the expanded uncertainties by [WelchSatter](#)'s total degrees-of-freedom or from the α -quantiles of the MC evaluations.

Usage

```
propagate(expr, data, type = c("stat", "raw", "sim"), cov = c("diag", "full"),
          df.tot = NULL, k = NULL, nsim = 1000000, alpha = 0.05,
          exp.uc = c("1st", "2nd"), check = TRUE, ...)
```

Arguments

expr	an expression, such as <code>expression(x/y)</code> .
data	a dataframe or matrix containing either a) the means (1^{st} row), standard error of the means (2^{nd} row) and optional degrees of freedom (3^{rd} row), b) raw measurement values or c) sampled distribution data generated from any of R's distributions or those implemented in this package (rDistr).
type	type of input data. Either <code>stat</code> for summary data, <code>raw</code> for experimental measurements or <code>sim</code> for distribution data. See 'Details'.
cov	use only "diag" onal variances, the "full" covariance matrix with off-diagonals or an external covariance matrix with the same column names as data. See 'Details'.
df.tot	an optional total degrees of freedom ν_{tot} that overrides the one obtained from WelchSatter .
k	an optional coverage factor that overrides the one obtained from WelchSatter .
nsim	the number of Monte Carlo simulations to be performed, minimum is 10000.
alpha	the 1 - confidence level.
exp.uc	Should the expanded uncertainty and confidence interval be calculated from the "1st"-order or "2nd"-order uncertainty?
check	logical. If TRUE, the Copula margins are fitted with a scaled/shifted t -distribution to check for proper construction, see summary.propagate .
...	other parameters to be supplied to future methods.

Details

The different type definitions are the following:

1) "stat", GUM 4.2: Statistical summary data (Mean, SEM, DOF), Type A evaluation

V1	V2	
Mean_1	Mean_2	=> Means in 1st row
SEM_1	SEM_2	=> SEMs (uncertainties) in 2nd row
(DOF_1)	(DOF_2)	=> optional DOFs in 3rd row

Covariance matrix: from SEMs² as diagonals (cov = "diag") or supplied externally.

2) "raw", GUM 4.2: Raw measurement values in rows, Type A evaluation

V1	V2	
x_1	y_1	\
x_2	y_2	\
x_3	y_3	
x_n	y_n	/

- Single raw values in rows 1...n

Mean, SEM and DOF are estimated from the data.

Covariance matrix: from estimated SEMs² as diagonals (cov = "diag"), full covariance matrix cov(data)/N (cov = "full") or supplied externally.

3) "sim", GUM 4.3: Random samples from distributions $x_i, y_i, \dots \sim F_1, F_2, \dots$, Type B evaluation

F1	F2	
x_1	y_1	\
x_2	y_2	\
x_3	y_3	
x_n	y_n	/

- MC samples in rows 1...n

Mean, SD and DOF are estimated from the data. The latter will be high ($N - 1$) and approximate a normal distribution.

Covariance matrix: from estimated SDs² as diagonals (cov = "diag"), full covariance matrix cov(data) (cov = "full") or supplied externally.

For all types: Expanded uncertainty U and confidence intervals from $U = k \cdot u$, $k = t_{ws,df}(1 - \alpha/2)$, CI = $[\hat{y} - U, \hat{y} + U]$, and empirical $[\alpha/2, 1 - \alpha/2]$ quantiles of the MC output distribution.

propagate tries "hard" to guess the data type and gives a comment (no change in settings!), *i.e.* **Type A summary** => 2/3 rows, **Type A raw measurement** => 3 < rows < 1000, **Type B distributions** => 1000 < rows.

The implemented methods are:

1) **Uncertainty propagation:**

The propagated uncertainties are calculated by first-/second-order Taylor expansion accounting for full covariance structure using matrix algebra.

The following transformations based on two variables x_1, x_2 illustrate the equivalence of the matrix-based approach with well-known classical notations:

First-order mean: $E[y] = f(\bar{x}_i)$

First-order variance: $\sigma_y^2 = \nabla \Sigma \nabla^T$:

$$\begin{aligned} [j_1 \ j_2] \begin{bmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \\ \sigma_2 \sigma_1 & \sigma_2^2 \end{bmatrix} \begin{bmatrix} j_1 \\ j_2 \end{bmatrix} &= j_1^2 \sigma_1^2 + 2j_1 j_2 \sigma_1 \sigma_2 + j_2^2 \sigma_2^2 \\ &= \underbrace{\sum_{i=1}^2 j_i^2 \sigma_i^2 + 2 \sum_{\substack{i=1 \\ i \neq k}}^2 \sum_{\substack{k=1 \\ k \neq i}}^2 j_i j_k \sigma_{ik}}_{\text{classical notation}} = \frac{1}{1!} \left(\sum_{i=1}^2 \frac{\partial f}{\partial x_i} \sigma_i \right)^2 \end{aligned}$$

Second-order mean: $E[y] = f(\bar{x}_i) + \frac{1}{2} \text{tr}(\mathbf{H}\Sigma)$:

$$\begin{aligned} \frac{1}{2} \text{tr} \begin{bmatrix} h_1 & h_2 \\ h_3 & h_4 \end{bmatrix} \begin{bmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \\ \sigma_2 \sigma_1 & \sigma_2^2 \end{bmatrix} &= \frac{1}{2} \text{tr} \begin{bmatrix} h_1 \sigma_1^2 + h_2 \sigma_1 \sigma_2 & h_1 \sigma_1 \sigma_2 + h_2 \sigma_2^2 \\ h_3 \sigma_1^2 + h_4 \sigma_1 \sigma_2 & h_3 \sigma_1 \sigma_2 + h_4 \sigma_2^2 \end{bmatrix} \\ &= \frac{1}{2} (h_1 \sigma_1^2 + h_2 \sigma_1 \sigma_2 + h_3 \sigma_1 \sigma_2 + h_4 \sigma_2^2) = \frac{1}{2!} \left(\sum_{i=1}^2 \frac{\partial}{\partial x_i} \sigma_i \right)^2 f \end{aligned}$$

Second-order variance: $\sigma_y^2 = \nabla \Sigma \nabla^T + \frac{1}{2} \text{tr}(\mathbf{H}\Sigma\mathbf{H}\Sigma)$:

$$\begin{aligned} \frac{1}{2} \text{tr} \begin{bmatrix} h_1 & h_2 \\ h_3 & h_4 \end{bmatrix} \begin{bmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \\ \sigma_2 \sigma_1 & \sigma_2^2 \end{bmatrix} \begin{bmatrix} h_1 & h_2 \\ h_3 & h_4 \end{bmatrix} \begin{bmatrix} \sigma_1^2 & \sigma_1 \sigma_2 \\ \sigma_2 \sigma_1 & \sigma_2^2 \end{bmatrix} &= \dots \\ &= \frac{1}{2} (h_1^2 \sigma_1^4 + 2h_1 h_2 \sigma_1^3 \sigma_2 + 2h_1 h_3 \sigma_1^3 \sigma_2 + h_2^2 \sigma_1^2 \sigma_2^2 + 2h_2 h_3 \sigma_1^2 \sigma_2^2 + h_3^2 \sigma_1^2 \sigma_2^2 + 2h_1 h_4 \sigma_1^2 \sigma_2^2 \\ &\quad + 2h_2 h_4 \sigma_1 \sigma_2^3 + 2h_3 h_4 \sigma_1 \sigma_2^3 + h_4^2 \sigma_2^4) = \frac{1}{2} (h_1 \sigma_1^2 + h_2 \sigma_1 \sigma_2 + h_3 \sigma_1 \sigma_2 + h_4 \sigma_2^2)^2 \\ &= \frac{1}{2!} \left(\left(\sum_{i=1}^2 \frac{\partial}{\partial x_i} \sigma_i \right)^2 f \right)^2 \end{aligned}$$

with $E(y)$ = expectation of y , σ_y^2 = variance of y , ∇ = the $p \times n$ gradient matrix with all partial first derivatives \mathbf{j}_i , Σ = the $p \times p$ covariance matrix, \mathbf{H} the Hessian matrix with all partial second derivatives \mathbf{h}_i , σ_i = the uncertainties and $\text{tr}(\cdot)$ = the trace (sum of diagonal) of a matrix. Note that because the Hessian matrices are symmetric, $\mathbf{h}_2 = \mathbf{h}_3$. For a detailed derivation, see 'References'. The second-order Taylor expansion corrects for bias in nonlinear expressions as the first-order Taylor expansion assumes linearity around \bar{X}_i .

For setups in which there is no symbolic derivation possible (i.e. `e <- expression(abs(x)) => "Function 'abs' is not in the derivatives table"`) the function automatically switches from symbolic (using `makeGrad` or `makeHess`) to numeric (`numGrad` or `numHess`) differentiation.

The function will try to evaluate the expression in an environment using `eval` which results in a significant speed enhancement (~ 10-fold). If that fails, evaluation is done over the rows of the simulated data using `apply`.

2) Monte Carlo simulation with a Gaussian Copula of t -Distributed Marginals:

According to Sklar's theorem, the joint distribution of correlated random variables X_1, \dots, X_d with marginal CDFs F_1, \dots, F_d can be expressed as:

$$F(x_1, \dots, x_d) = C_{\mathbf{R}}^{\text{Gauss}}(F_1(x_1), \dots, F_d(x_d))$$

where $C_{\mathbf{R}}^{\text{Gauss}}$ is the Gaussian copula with correlation matrix \mathbf{R} . For t -distributed marginals with individual degrees of freedom ν_1, \dots, ν_d , the marginal CDFs are:

$$F_i(x_i) = F_{t, \nu_i} \left(\frac{x_i - \mu_i}{\sigma_i} \right)$$

where μ_i and σ_i are the location and scale parameters, and F_{t, ν_i} is the CDF of the standard t -distribution with ν_i degrees of freedom. Sampling is as follows:

1. Convert covariance matrix Σ to correlation matrix \mathbf{R} : $\mathbf{R}_{ij} = \Sigma_{ij} / \sqrt{\Sigma_{ii} \Sigma_{jj}}$
2. Generate $\mathbf{v} \sim C_{\mathbf{R}}^{\text{Gauss}}$ from the Gaussian copula (uniform marginals on $[0,1]$)
3. Transform: $z_i = F_{t, \nu_i}^{-1}(\mathbf{v}_i)$ for each margin
4. Apply variance correction: $z_i^* = z_i / \sqrt{\nu_i / (\nu_i - 2)}$ for $\nu_i > 2$
5. Scale and shift: $X_i = \mu_i + \sigma_i \cdot z_i^*$ giving final MC-simulated matrix \mathbf{X}^{MC} .

The variance correction in step 3 is necessary because the standard t -distribution has variance $\nu_i / (\nu_i - 2)$ rather than unity. The Gaussian copula preserves the correlation structure \mathbf{R} while allowing each marginal to have its own degrees of freedom ν_i , making it suitable for GUM Supplement 1 uncertainty propagation with heterogeneous Type A uncertainties.

The function conducts the following three additional checks, visible in `summary.propagate`:

1. Frobenius Norm of input covariance matrix Σ to MC-derived covariance matrix $\hat{\Sigma}^{\text{MC}}$:

$$\varepsilon_F = \frac{\sqrt{\sum_{i=1}^n \sum_{j=1}^n (\hat{\Sigma}_{ij}^{\text{MC}} - \Sigma_{ij})^2}}{\sqrt{\sum_{i=1}^n \sum_{j=1}^n \Sigma_{ij}^2}}$$

2. Frobenius Norm of input correlation matrix \mathbf{R} to MC-derived correlation matrix $\hat{\mathbf{R}}^{\text{MC}}$:

$$\varepsilon_F = \frac{\sqrt{\sum_{i=1}^n \sum_{j=1}^n (\hat{\mathbf{R}}_{ij}^{\text{MC}} - \mathbf{R}_{ij})^2}}{\sqrt{\sum_{i=1}^n \sum_{j=1}^n \mathbf{R}_{ij}^2}}$$

3. For each marginal component X_i of the constructed copula, a shifted and scaled t -distribution is fitted independently by estimating $\hat{\mu}_i$, $\hat{\sigma}_i$, and $\hat{\nu}_i$, checking for similarity of the margins to the input structure.

Value

A short printed output of the results (for a more detailed output use `summary(object)`) and a list with the following components:

<code>gradient</code>	the symbolic gradient vector ∇ of partial first-order derivatives.
<code>evalGrad</code>	the evaluated gradient vector ∇ of partial first-order derivatives, also known as "sensitivities". See summary.propagate .
<code>hessian</code>	the symbolic Hessian matrix \mathbf{H} of partial second-order derivatives.
<code>evalHess</code>	the evaluated Hessian matrix \mathbf{H} of partial second-order derivatives.
<code>rel.contr</code>	the relative contributions, RC_i , see summary.propagate .
<code>covMat</code>	the covariance matrix Σ used for Monte Carlo simulation and uncertainty propagation (input).
<code>covMat.MC</code>	the estimated covariance matrix $\hat{\Sigma}^{\text{MC}}$ derived from the Monte Carlo simulation (output).
<code>corMat</code>	the Σ -converted correlation matrix \mathbf{R} used for Monte Carlo simulation (input).
<code>corMat.MC</code>	the estimated correlation matrix $\hat{\mathbf{R}}^{\text{MC}}$ derived from the Monte Carlo simulation (output).
<code>frobCOV</code>	the Frobenius norm ε_F of input and Copula-derived covariance matrices.
<code>frobCOR</code>	the Frobenius norm ε_F of input and Copula-derived correlation matrices.
<code>ws.df</code>	the Welch-Satterthwaite degrees of freedom ν_{ws} , as obtained from WelchSatter .
<code>k</code>	the coverage factor k , as calculated by $t(1 - (\alpha/2), \nu_{\text{ws}})$.
<code>u.exp</code>	the expanded uncertainty, $U = k \cdot u$, where u is derived from the first- or second-order propagation, depending on the setting of <code>exp.uc</code> .
<code>resSIM</code>	a vector containing the <code>nsim</code> values obtained from the expression evaluations $f(x_{m,i})$ of the simulated data in <code>datSIM</code> .
<code>datSIM</code>	a vector containing the <code>nsim</code> simulated multivariate values for each variable in column format.
<code>datSIM2</code>	a second Copula function MC simulation to be used as matrix \mathbf{B} for Sobol sensitivity analysis, see sobol .
<code>prop</code>	a summary vector containing first-/second-order expectations and uncertainties from propagation as well as the confidence interval based on the t -distribution.
<code>sim</code>	a summary vector containing the mean, standard deviation, median, MAD from MC evaluation, as well as the confidence interval based on the α -quantiles.

expr	the original expression expr.
data	a matrix containing the given (type = "stat") or estimated (type = "raw/sim") means, uncertainties and degrees-of-freedom.
alpha	the original α -level.
nsim	the number of Monte Carlo samples used for the Copula.
check	a matrix containing the means, uncertainties and degrees-of-freedom derived from fitting the Copula margins with a scaled/shifted t -distribution.
type	the original type definition, important for, e.g., sobol .

Author(s)

Andrej-Nikolai Spiess

References**Uncertainty propagation (in general):**

An Introduction to error analysis.

Taylor JR.

University Science Books (1996), New York.

Evaluation of measurement data - Guide to the expression of uncertainty in measurement.

JCGM 100:2008 (GUM 1995 with minor corrections).

https://www.bipm.org/documents/20126/2071204/JCGM_100_2008_E.pdf/.

Evaluation of measurement data - Supplement 1 to the Guide to the expression of uncertainty in measurement - Propagation of distributions using a Monte Carlo Method.

JCGM 101:2008.

https://www.bipm.org/documents/20126/2071204/JCGM_100_2008_E.pdf/.

Higher-order Taylor expansion:

On higher-order corrections for propagating uncertainties.

Wang CM & Iyer HK.

Metrologia (2005), **42**: 406-410.

Propagation of uncertainty: Expressions of second and third order uncertainty with third and fourth moments.

Mekid S & Vaja D.

Measurement (2008), **41**: 600-609.

Matrix algebra for uncertainty propagation:

An Introduction to Error Propagation: Derivation, Meaning and Examples of Equation $C_y = F_x C_x F_x^t$.

<https://www.research-collection.ethz.ch/handle/20.500.11850/82620>.

Second order nonlinear uncertainty modeling in strapdown integration using MEMS IMUs.

Zhang M, Hol JD, Slot L, Luinge H.

2011 Proceedings of the 14th International Conference on Information Fusion (FUSION) (2011).

Uncertainty propagation in non-linear measurement equations.

Mana G & Pennechi F.

Metrologia (2007), **44**: 246-251.

A compact tensor algebra expression of the law of propagation of uncertainty.
Bouchot C, Quilantan JLC, Ochoa JCS.

Metrologia (2011), **48**: L22-L28.

Nonlinear error propagation law.

Kubacek L.

Appl Math (1996), **41**: 329-345.

Monte Carlo simulation (normal- and t-distribution):

MUSE: computational aspects of a GUM supplement 1 implementation.

Mueller M, Wolf M, Roesslein M.

Metrologia (2008), **45**: 586-594.

Copulas for uncertainty analysis.

Possolo A.

Metrologia (2010), **47**: 262-271.

Random variables, joint distribution functions, and copulas.

Sklar A.

Kybernetika (1973), **9**: 449-460.

Multivariate normal distribution:

Stochastic Simulation.

Ripley BD.

Stochastic Simulation (1987). Wiley. Page 98.

Testing for normal distribution:

Testing for Normality.

Thode Jr. HC.

Marcel Dekker (2002), New York.

Approximating the Shapiro-Wilk W-test for non-normality.

Royston P.

Stat Comp (1992), **2**: 117-119.

Examples

```
## ATTENTION: all examples with nsim = 10000
## and check = FALSE for reduced CRAN check time.
## It is advised to use nsim = 1000000 (default)
## and check = TRUE in real-life setup.

## Example without given degrees-of-freedom.
EXPR1 <- expression(x/y)
x <- c(5, 0.01)
y <- c(1, 0.01)
DF1 <- cbind(x, y)
propagate(expr = EXPR1, data = DF1, type = "stat",
          nsim = 10000, check = FALSE)

## Same example with given degrees-of-freedom
## => third row in input 'data'.
EXPR2 <- expression(x/y)
x <- c(5, 0.01, 12)
y <- c(1, 0.01, 5)
```

```

DF2 <- cbind(x, y)
propagate(expr = EXPR2, data = DF2, type = "stat",
          nsim = 10000, check = FALSE)

##### GUM 2008 (1) #####
## Example in Annex H.1 from the GUM 2008 manual
## (see 'References'), an end gauge calibration
## study. We use total df = 16 and alpha = 0.01,
## as detailed in GUM H.1.6.
EXPR3 <- expression(ls + d - ls * (da * the + as * dt))
ls <- c(50000623, 25)
d <- c(215, 9.7)
da <- c(0, 0.58E-6)
the <- c(-0.1, 0.41)
as <- c(11.5E-6, 1.2E-6)
dt <- c(0, 0.029)
DF3 <- cbind(ls, d, da, the, as, dt)
propagate(expr = EXPR3, data = DF3, type = "stat",
          nsim = 10000, check = FALSE, df.tot = 16, alpha = 0.01)
## 1st order => propagate: u.1 = 31.71, GUM H.1.4/H.6c: u = 32
## Expanded uncertainty => propagate: 92.62, GUM H.1.6: 93
## 2nd order => propagate: u.2 = 33.91115, GUM H.1.7: u = 34.
## Also similar to the non-matrix-based approach
## in Wang et al. (2005, page 408): u1 = 33.91115.
## NOTE: After second-order correction ("u.2"),
## uncertainty is more similar to the uncertainty
## obtained from Monte Carlo simulation!

##### GUM 2008 (2) #####
## Example in Annex H.2 from the GUM 2008 manual
## (see 'References'), simultaneous resistance
## and reactance measurement.
data(H.2)

## This gives exactly the means, uncertainties and
## correlations as given in Table H.2:
colMeans(H.2)
sqrt(colVarsC(H.2))/sqrt(5)
cor(H.2)

## H.2.3 Approach 2 using the raw
## measurement values and full covariance
EXPR4 <- expression((V/I) * cos(phi)) ## R
propagate(expr = EXPR4, data = H.2, type = "raw", cov = "full",
          nsim = 10000, check = FALSE)
## This gives exactly the means and uncertainties
## as given in H.2.4, Table H.4

## H.2.3 Approach 2 using the raw
## measurement values and only diagonals (no correlation)
propagate(expr = EXPR4, data = H.2, type = "raw",
          nsim = 10000, check = FALSE)

```

```

## This gives exactly the means and uncertainties
## as given in H.2.4, Table H.5

##### GUM 2008 Supplement 1 (1) #####
## Example from 9.2.2 of the GUM 2008 Supplement 1
## (see 'References'), normally distributed input
## quantities. Assign values as in 9.2.2.1.
EXPR5 <- expression(X1 + X2 + X3 + X4)
X1 <- c(0, 1)
X2 <- c(0, 1)
X3 <- c(0, 1)
X4 <- c(0, 1)
DF5 <- cbind(X1, X2, X3, X4)
propagate(expr = EXPR5, data = DF5, type = "stat",
          nsim = 10000, check = FALSE)
## This will give exactly the same results as in
## 9.2.2.6, Table 2.

##### GUM 2008 Supplement 1 (2) #####
## Example from 9.3 of the GUM 2008 Supplement 1
## (see 'References'), mass calibration.
## Formula 24 in 9.3.1.3 and values as in 9.3.1.4, Table 5.
EXPR6 <- expression((Mrc + dMrc) * (1 + (Pa - Pa0) * ((1/Pw) - (1/Pr))) - Mnom)
Mrc <- rnorm(1E5, 100000, 0.050)
dMrc <- rnorm(1E5, 1.234, 0.020)
Pa <- runif(1E5, 1.10, 1.30) ## E(Pa) = 1.2, (b-a)/2 = 0.1
Pw <- runif(1E5, 7000, 9000) ## E(Pw) = 8000, (b-a)/2 = 1000
Pr <- runif(1E5, 7950, 8050) ## E(Pr) = 8000, (b-a)/2 = 50
Pa0 <- 1.2
Mnom <- 100000
DF6 <- cbind(Mrc, dMrc, Pa, Pw, Pr, Pa0, Mnom)
propagate(expr = EXPR6, data = DF6, type = "sim", check = FALSE)
## This will give exactly the same results as in
## 9.3.2.3, Table 6

##### GUM 2008 Supplement 1 (3) #####
## Example from 9.4 of the GUM 2008 Supplement 1
## (see 'References'), comparison loss in microwave
## power meter calibration, zero covariance.
## Formula 28 in 9.4.1.5 and values as in 9.4.1.7.
EXPR7 <- expression(X1^2 - X2^2)
X1 <- c(0.050, 0.005)
X2 <- c(0, 0.005)
DF7 <- cbind(X1, X2)
propagate(expr = EXPR7, data = DF7, type = "stat",
          nsim = 10000, check = FALSE)
## This will give exactly the same results as in
## 9.4.2.2.7, Table 8, x1 = 0.050.

##### GUM 2008 Supplement 1 (4) #####
## Example from 9.5 of the GUM 2008 Supplement 1
## (see 'References'), gauge block calibration.
## Assignment of PDF's as in Table 10 of 9.5.2.1.

```

```

EXPR8 <- expression(Ls + D + d1 + d2 - Ls * (da * (t0 + Delta) + as * dt) - Lnom)
Lnom <- 50000000
Ls <- propagate::rst(10000, mean = 50000623, sd = 25, df = 18)
D <- propagate::rst(10000, mean = 215, sd = 6, df = 24)
d1 <- propagate::rst(10000, mean = 0, sd = 4, df = 5)
d2 <- propagate::rst(10000, mean = 0, sd = 7, df = 8)
as <- runif(10000, 9.5E-6, 13.5E-6)
t0 <- rnorm(10000, -0.1, 0.2)
Delta <- propagate::rarcisin(10000, -0.5, 0.5)
da <- propagate::rctrp(10000, -1E-6, 1E-6, 0.1E-6)
dt <- propagate::rctrp(10000, -0.050, 0.050, 0.025)
DF8 <- cbind(Ls, D, d1, d2, as, t0, Delta, da, dt, Lnom)
propagate(expr = EXPR8, data = DF8, type = "sim", cov = "diag", alpha = 0.01,
          nsim = 10000, check = FALSE)
## This gives "fairly" the same results as in 9.5.4.2, Table 11,
## especially when comparing u.MC with u.2!
## GUM 2008 gives 32 and 36, respectively.

```

Description

These are random sample generators for 26 different continuous distributions which are not readily available as [Distributions](#) in R. Some of them are implemented in other specialized packages (i.e. `rsn` in package 'sn' or `rtrapezoid` in package 'trapezoid'), but here they are collated in a way that makes them easily accessible for Monte Carlo-based uncertainty propagation.

Details

Random samples can be drawn from the following 26 distributions:

- 1) Skewed-normal distribution: `propagate::rsn(n, location = 0, scale = 1, shape = 0)`
- 2) Generalized normal distribution: `propagate::rgnorm(n, alpha = 1, xi = 1, kappa = -0.1)`
- 3) Scaled and shifted t-distribution: `propagate::rst(n, mean = 0, sd = 1, df = 2)`
- 4) Gumbel distribution: `propagate::rgumbel(n, location = 0, scale = 1)`
- 5) Johnson SU distribution: `propagate::rJSU(n, xi = 0, lambda = 1, gamma = 1, delta = 1)`
- 6) Johnson SB distribution: `propagate::rJSB(n, xi = 0, lambda = 1, gamma = 1, delta = 1)`
- 7) 3P Weibull distribution: `propagate::rweibull2(n, location = 0, shape = 1, scale = 1)`
- 8) 4P Beta distribution: `propagate::rbeta2(n, alpha1 = 1, alpha2 = 1, a = 0, b = 0)`
- 9) Triangular distribution: `propagate::rtriang(n, a = 0, b = 1, c = 0.5)`
- 10) Trapezoidal distribution: `propagate::rtrap(n, a = 0, b = 1, c = 2, d = 3)`
- 11) Laplacian distribution: `propagate::rlaplace(n, mean = 0, sigma = 1)`
- 12) Arcsine distribution: `propagate::rarcisin(n, a = 2, b = 1)`
- 13) von Mises distribution: `propagate::rmises(n, mu = 1, kappa = 3)`
- 14) Curvilinear Trapezoidal distribution: `propagate::rctrp(n, a = 0, b = 1, d = 0.1)`
- 15) Generalized trapezoidal distribution:
`propagate::rgtrap(n, min = 0, mode1 = 1/3, mode2 = 2/3, max = 1, n1 = 2, n3 = 2, alpha = 1)`

16) Inverse Gaussian distribution: `propagate::rinvgauss(n, mean = 1, dispersion = 1)` 17) Generalized Extreme Value distribution: `propagate::rgevd(n, loc = 0, scale = 1, shape = 0)` with n = number of samples.

18) Inverse Gamma distribution: `propagate::rinvgamma(n, shape = 1, scale = 5)`

19) Rayleigh distribution: `propagate::rrayleigh(n, mu = 1, sigma = 1)`

20) Burr distribution: `propagate::rburr(n, k = 1)`

21) Chi distribution: `propagate::rchi(n, nu = 5)`

22) Inverse Chi-Square distribution: `propagate::rinvchisq(n, nu = 5)`

23) Cosine distribution: `propagate::rcosine(n, mu = 5, sigma = 1)`

24) Pareto distribution: `propagate::rpareto(n, scale = 0, shape = 1)`

25) Levy distribution: `propagate::rlevy(n, loc = 0, scale = 1)`

26) Gompertz distribution: `propagate::rgompertz(n, shape = 0, rate = 1)`

1) - 12), 17) - 22, 24-26) use the inverse cumulative distribution function as mapping functions for `runif` (**Inverse Transform Method**):

(1) $U \sim \mathcal{U}(0, 1)$

(2) $Y = F^{-1}(U, \beta)$

16) uses binomial selection from a χ^2 -distribution.

13) - 15), 23) employ "Rejection Sampling" using a uniform envelope distribution (**Acceptance Rejection Method**):

(1) Find $F_{max} = \max(F([x_{min}, x_{max}], \beta)$

(2) $U_{max} = 1/(x_{max} - x_{min})$

(3) $A = F_{max}/U_{max}$

(4) $U \sim \mathcal{U}(0, 1)$

(5) $X \sim \mathcal{U}(x_{min}, x_{max})$

(6) $Y \iff U \leq A \cdot \mathcal{U}(X, x_{min}, x_{max})/F(X, \beta)$

These four distributions are coded in a vectorized approach and are hence not much slower than implementations in C/C++ (0.2 - 0.5 sec for 100000 samples; 3 GHz Quadcore processor, 4 GByte RAM). The code for the random generators is in file "distr-samplers.R".

Value

A vector with n samples from the corresponding distribution.

Author(s)

Andrej-Nikolai Spiess

References

Rejection Sampling in R:

Rejection Sampling.

<https://www.r-bloggers.com/2011/06/rejection-sampling/>.

Rejection Sampling in general:

Non-uniform random variate generation.

Devroye L.

Springer-Verlag, New York (1986).

Distributions:

Continuous univariate distributions, Volume 1.

Johnson NL, Kotz S and Balakrishnan N.
Wiley Series in Probability and Statistics, 2.ed (2004).

See Also

See also [propagate](#), in which GUM 2008 Supplement 1 examples use these distributions.

Examples

```
## Not run:
## First we create random samples from the
## von Mises distribution.
X <- propagate::rmises(10000, mu = 1, kappa = 2)

## Then we fit all available distributions
## with 'fitDistr'.
fitDistr(X, nbin = 200, distsel = 1:22)
## => von Mises wins! (lowest BIC)

## End(Not run)
```

sobol

Compute Sobol Sensitivity Indices from a propagate object

Description

Compute first-order and total-order Sobol sensitivity indices from an object returned by [propagate](#), by performing evaluations based on the MC simulated samples of the provided propagate object, or from external matrices/expressions.

Usage

```
sobol(prop = NULL, A = NULL, B = NULL, expr = NULL,
      method = c("jansen", "sobol", "saltelli", "honna"))
```

Arguments

prop	A propagate object.
A	An MC simulated matrix.
B	A second MC simulated matrix, derived from the same distributions.
expr	an expression to be evaluated.
method	Method for sensitivity indices. See 'Details'.

Details**Sobol (1993) estimator:**

$$S_i = \frac{1}{V}, \mathbb{E} \left[f(\mathbf{B}) \left(f(\mathbf{A}_B^{(i)}) - f(\mathbf{A}) \right) \right]$$

Estimates the first-order (main effect) Sobol index, *i.e.* the fraction of output variance explained by input X_i alone, excluding all interaction effects. This is the original Monte Carlo estimator associated with the Sobol variance decomposition.

Saltelli (2002) estimator:

$$S_i = \frac{1}{V}, \mathbb{E} \left[f(\mathbf{B}) \left(f(\mathbf{A}_B^{(i)}) - f(\mathbf{A}) \right) \right]$$

$$S_{T_i} = \frac{1}{2V}, \mathbb{E} \left[\left(f(\mathbf{A}) - f(\mathbf{A}_B^{(i)}) \right)^2 \right]$$

Provides both first-order and total-order Sobol indices using a single sampling design. This formulation improves numerical efficiency over the original Sobol estimator and is widely used in practice.

Homma-Saltelli (1996) estimator:

$$S_{T_i} = \frac{1}{V}, \mathbb{E} \left[f(\mathbf{A}) \left(f(\mathbf{A}) - f(\mathbf{A}_B^{(i)}) \right) \right]$$

Estimates the total-order Sobol index only, *i.e.* the total contribution of input X_i to output variance including all interaction effects. No first-order estimator is defined in this method.

Jansen (1999) estimator (recommended):

$$S_i = 1 - \frac{1}{2V}, \mathbb{E} \left[\left(f(\mathbf{B}) - f(\mathbf{A}_B^{(i)}) \right)^2 \right]$$

$$S_{T_i} = \frac{1}{2V}, \mathbb{E} \left[\left(f(\mathbf{A}) - f(\mathbf{A}_B^{(i)}) \right)^2 \right]$$

Provides low-variance, numerically stable estimators for both first-order and total-order Sobol indices. This formulation avoids covariance terms and is considered best practice in modern global sensitivity analysis.

Value

A list with the following components:

S	Vector of first-order indices S_i .
ST	Vector of total-order indices S_{T_i} .

References

Variance based sensitivity analysis of model output. Design and estimator for the total sensitivity index.

Saltelli A, Annoni P, Azzini I, Campolongo F, Ratto M, Tarantola S.
Comp Phys Comm (2010), **181**: 259-270.

Making best use of model evaluations to compute sensitivity indices.

Saltelli A.

Comp Phys Comm (2002), **145**: 280-297.

Global sensitivity indices for nonlinear mathematical models and their Monte Carlo estimates.

Sobol IM.

Math Comp Sim (2001), **55**: 271-280.

Importance measures in global sensitivity analysis of nonlinear models.

Homma T, Saltelli A.

Rel Engineer & Sys Safety (1996), **52**: 1-17.

Analysis of variance designs for model output.

Jansen MJW.

Comp Phys Comm (1999), **117**: 35-43.

An importance quantification technique in uncertainty analysis for computer models.

Ishigami T, Homma T.

Japan Atomic Energy Research Inst Tokyo (1989).

Examples

```
## Example from 'propagate'
EXPR1 <- expression(x/y)
x <- c(5, 0.01, 12)
y <- c(1, 0.01, 5)
DF1 <- cbind(x, y)
RES1 <- propagate(expr = EXPR1, data = DF1, type = "stat", nsim = 10000, check = FALSE)
sobol(RES1)

## Classical Ishigami function for gauging
A <- cbind(
  x1 = runif(1e6, -pi, pi),
  x2 = runif(1e6, -pi, pi),
  x3 = runif(1e6, -pi, pi)
)
B <- cbind(
  x1 = runif(1e6, -pi, pi),
  x2 = runif(1e6, -pi, pi),
  x3 = runif(1e6, -pi, pi)
)
EXPR <- expression(sin(x1) + 7 * (sin(x2))^2 + 0.1 * x3^4 * sin(x1))
sobol(A = A, B = B, expr = EXPR, method = "jansen")
# => X1: 0.559, X2: 0.442, X3: 0.242
# => Homma & Saltelli (1996), Table 4: X1: 0.557, X2: 0.444, X3: 0.241
```

statVec

Transform an input vector into one with defined mean and standard deviation

Description

Transforms an input vector into one with defined μ and σ by using a scaled-and-shifted Z-transformation.

Usage

```
statVec(x, mean, sd)
```

Arguments

x the input vector to be transformed.
 mean the desired mean of the created vector.
 sd the desired standard deviation of the created vector.

Details

Calculates vector V using a Z-transformation of the input vector X and subsequent scaling by sd and shifting by mean:

$$V = \frac{X - \mu_X}{\sigma_X} \cdot \text{sd} + \text{mean}$$

Value

A vector with defined μ and σ .

Author(s)

Andrej-Nikolai Spiess

Examples

```
## Create a 10-sized vector with mean = 10 and s.d. = 1.
x <- rnorm(10, 5, 2)
mean(x) ## => mean is not 5!
sd(x) ## => s.d. is not 2!

z <- statVec(x, 5, 2)
mean(z) ## => mean is 5!
sd(z) ## => s.d. is 2!
```

stochContr	<i>Stochastic contribution analysis of Monte Carlo simulation-derived propagated uncertainty</i>
------------	--

Description

Conducts a "stochastic contribution analysis" by calculating the change in propagated uncertainty when each of the simulated variables is kept constant at its mean, i.e. the uncertainty is removed.

Usage

```
stochContr(prop, plot = TRUE)
```

Arguments

prop	a propagate object.
plot	logical. If TRUE, a boxplot with the original and mean-value propagated distribution.

Details

This function takes the Monte Carlo simulated data X_n from a `propagate` object (`...$datSIM`), sequentially substitutes each variable β_i by its mean $\bar{\beta}_i$ and then re-evaluates the output distribution $Y_n = f(\beta, X_n)$. Optional boxplots are displayed that compare the original $Y_n(\text{orig})$ to those obtained from removing σ from each β_i . Finally, the relative contribution C_i for all β_i is calculated by $C_i = \sigma(Y_n(\text{orig})) - \sigma(Y_n)$, and divided by its sum so that $\sum_{i=1}^n C_i = 1$.

Value

The relative contribution C_i for all variables.

Author(s)

Andrej-Nikolai Spiess

Examples

```
a <- c(15, 1)
b <- c(100, 5)
c <- c(0.5, 0.02)
DAT <- cbind(a, b, c)
EXPR <- expression(a * b^sin(c))
RES <- propagate(EXPR, DAT, nsim = 100000)
stochContr(RES)
```

summary.propagate

Summary function for 'propagate' objects

Description

Provides a printed summary of the results obtained by `propagate`, with many GUM (2008) and GUM Supplement 1 (2008) relevant statistics, as outlined in 'Details'.

Usage

```
## S3 method for class 'propagate'
summary(object, normality = FALSE, ...)
```

Arguments

object	an object returned from propagate .
normality	logical. If TRUE, the three repeated subsampling normality tests are performed. See 'Details'.
...	other parameters for future methods.

Details

summary.propagate provides an extensive output and overview on the results of [propagate](#):

For classical JCGM 100:2008 output:

1. Results of the first- (mean.1, u.1) and second-order (mean.2, u.2) uncertainty propagation, as well as from MC simulation (mean.MC, u.MC, median.MC, mad.MC), including confidence intervals
2. The Welch-Satterthwaite degrees of freedom ws.df, as obtained from [WelchSatter](#)
3. The coverage factor $k = t_{\text{ws.df}}(1 - \alpha/2)$
4. The expanded uncertainty $U = k \cdot u$, where u can be either first-order u.1 or second-order u.2, see [propagate](#)
5. The symbolic gradient matrix ∇ , also often termed **G**, **J** or **C_x** (JCGM 102:2011)
6. The evaluated gradient matrix, also known as "sensitivities", $c_i = \text{eval}(\partial f / \partial x_i)$
7. The relative contribution (summing up to 1)

$$\text{RC}_{ii} = \text{diag} \left(\frac{|c_i \cdot c_j \cdot \Sigma_{ij}|}{\sum_{k,\ell} |c_k \cdot c_\ell \cdot \Sigma_{k\ell}|} \right)$$

8. The symbolic Hessian matrix **H**, also often termed ∇^2
9. The evaluated Hessian matrix $h_{ij} = \text{eval} \left(\frac{\partial^2 f}{\partial x_i \partial x_j} \right)$
10. The input covariance matrix Σ , as provided from (i) the uncertainties in the 2nd row of the input data, (ii) estimation from the raw data, or (iii) an externally supplied one. Also often termed **V** or **U_x** (JCGM 102:2011)

For JCGM 101:2008, but extended with checks of input parameters for the Copula vs. the output attributes of the MC-generated random matrix \mathbf{X}^{MC} :

11. The covariance estimated from the MC simulations of the Copula distribution, $\hat{\Sigma}^{\text{MC}} = \text{cov}(\mathbf{X}^{\text{MC}})$
12. The Frobenius norm of the estimated vs. input covariance matrix, $\|\hat{\Sigma}^{\text{MC}} - \Sigma\|_F$
13. The correlation matrix **R** derived from Σ (by [cov2cor](#)) to construct the Gaussian Copula with t -margins, $C^{\text{Gauss}, t}$
14. The correlation matrix estimated from the MC simulations of the Copula distribution, $\hat{\mathbf{R}}^{\text{MC}} = \text{cor}(\mathbf{X}^{\text{MC}})$
15. The Frobenius norm of the estimated vs. input correlation matrix, $\|\hat{\mathbf{R}}_{\text{MC}} - \mathbf{R}\|_F$

16. A comparison of Copula-input and MC-derived moments/DOFs, to check for similarity and success of the Copula construction/MC sampling

Further repeated subsampling tests for normality on the evaluated MC samples, $Y = \mathbf{X}^{\text{MC}}$:

17. Skewness and Excess Kurtosis
18. Shapiro-Wilk test (2000 repeats, 5000 samples)
19. Anderson-Darling test (1000 repeats, 10000 samples)
20. Lilliefors test (1000 repeats, 10000 samples) For the three tests, the median of the log p -values is calculated, as the resulting p -distribution is more or less log-normal, $\text{med}(P) = \exp(\text{med}(\log(P)))$.

Value

A printed output with the items listed under 'Details'.

Author(s)

Andrej-Nikolai Spiess

References

See [propagate](#)

Examples

```
EXPR1 <- expression(x^2 * sin(y))
x <- c(5, 0.01)
y <- c(1, 0.01)
DF1 <- cbind(x, y)
RES1 <- propagate(expr = EXPR1, data = DF1, type = "stat",
                 nsim = 10000, check = TRUE)
summary(RES1)
```

WelchSatter

Welch-Satterthwaite approximation to the 'effective degrees of freedom'

Description

Calculates the Welch-Satterthwaite approximation to the 'effective degrees of freedom' by using the samples' uncertainties and degrees of freedoms, as described in Welch (1947) and Satterthwaite (1946). External sensitivity coefficients can be supplied optionally.

Usage

```
WelchSatter(ui, ci = NULL, df = NULL, df.tot = NULL, uc = NULL, alpha = 0.05, k = NULL)
```

Arguments

ui	the uncertainties u_i for each variable x_i .
ci	the sensitivity coefficients $c_i = \partial y / \partial x_i$.
df	the degrees of freedom for the samples, ν_i .
df . tot	an optional known total degrees of freedom for the system, ν_{tot} . Overrides the internal calculation of ν_{ws} .
uc	the combined uncertainty, $u(y)$.
alpha	the significance level for the t-statistic. See 'Details'.
k	an external coverage factor, say 2, that overrides the one obtained from defining alpha.

Details

$$\nu_{\text{eff}} \approx \frac{u(y)^4}{\sum_{i=1}^n \frac{(c_i u_i)^4}{\nu_i}}, \quad k = t(1 - (\alpha/2), \nu_{\text{eff}}), \quad u_{\text{exp}} = k u(y)$$

Value

A list with the following items:

ws . df	the 'effective degrees of freedom'.
k	the coverage factor for calculating the expanded uncertainty.
u . exp	the expanded uncertainty u_{exp} .

Author(s)

Andrej-Nikolai Spiess

References

An Approximate Distribution of Estimates of Variance Components.

Satterthwaite FE.

Biometrics Bulletin (1946), **2**: 110-114.

The generalization of "Student's" problem when several different population variances are involved.

Welch BL.

Biometrika (1947), **34**: 28-35.

Examples

Taken from GUM H.1.6, 4).

WelchSatter(ui = c(25, 9.7, 2.9, 16.6), df = c(18, 25.6, 50, 2), uc = 32, alpha = 0.01)

Index

- * **algebra**
 - bigcor, 2
 - cor2cov, 4
 - fitDistr, 7
 - interval, 10
 - makeDat, 13
 - makeDerivs, 14
 - mixCov, 17
 - moments, 19
 - numDerivs, 20
 - predictNLS, 22
 - propagate, 25
 - rDistr, 34
 - sobol, 36
 - statVec, 38
 - stochContr, 39
 - WelchSatter, 42
 - * **array**
 - makeDerivs, 14
 - mixCov, 17
 - moments, 19
 - numDerivs, 20
 - predictNLS, 22
 - propagate, 25
 - sobol, 36
 - * **datasets**
 - datasets, 5
 - * **matrix**
 - bigcor, 2
 - cor2cov, 4
 - interval, 10
 - statVec, 38
 - stochContr, 39
 - WelchSatter, 42
 - * **models**
 - plot.propagate, 21
 - summary.propagate, 40
 - * **multivariate**
 - bigcor, 2
 - cor2cov, 4
 - interval, 10
 - makeDerivs, 14
 - mixCov, 17
 - moments, 19
 - numDerivs, 20
 - predictNLS, 22
 - propagate, 25
 - sobol, 36
 - statVec, 38
 - stochContr, 39
 - WelchSatter, 42
 - * **nonlinear**
 - plot.propagate, 21
 - summary.propagate, 40
 - * **univariate**
 - fitDistr, 7
 - makeDat, 13
 - rDistr, 34
 - * **univar**
 - matrixStats, 16
- apply, 28
- BIC, 7, 9
- bigcor, 2
- cbind, 13
- colVarsC (matrixStats), 16
- cor, 2, 3
- cor2cov, 4
- cov, 2
- cov2cor, 4, 41
- datasets, 5
- Distributions, 34
- distributions, 25
- environment, 20
- eval, 28
- evalDerivs (makeDerivs), 14

fitDistr, 7

H.2 (datasets), 5
H.3 (datasets), 5
H.4 (datasets), 5
hist, 21

interval, 10

kurtosis (moments), 19

makeDat, 13
makeDerivs, 14
makeGrad, 28
makeGrad (makeDerivs), 14
makeHess, 28
makeHess (makeDerivs), 14
matrix, 3
matrixStats, 16
mixCov, 17
moments, 19

nls, 22
numDerivs, 20
numGrad, 28
numGrad (numDerivs), 20
numHess, 28
numHess (numDerivs), 20

plot.propagate, 21
predict.nls, 22
predictNLS, 22
propagate, 7, 13, 14, 17, 21–23, 25, 36, 40–42

rDistr, 25, 34
rowVarsC (matrixStats), 16
runif, 35

skewness (moments), 19
sobol, 29, 30, 36
statVec, 38
stochContr, 39
summary.propagate, 25, 28, 29, 40

var, 16

WelchSatter, 25, 29, 41, 42