

# Package ‘terrainmeshr’

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**Type** Package

**Title** Triangulate and Simplify 3D Terrain Meshes

**Version** 1.0.1

**Description**

Provides triangulations of regular height fields, based on the methods described in “Fast Polygonal Approximation of Terrains and Height Fields” Michael Garland and Paul S. Heckbert (1995) <<https://www.mgarland.org/files/papers/scape.pdf>> using code from the 'hmm' library written by Michael Fogleman <<https://github.com/fogleman/hmm>>.

**License** MIT + file LICENSE

**Encoding** UTF-8

**RoxygenNote** 7.3.3

**URL** <https://github.com/tylermorganwall/terrainmeshr>

**BugReports** <https://github.com/tylermorganwall/terrainmeshr/issues>

**NeedsCompilation** yes

**Author** Tyler Morgan-Wall [aut, cph, cre] (ORCID: <<https://orcid.org/0000-0002-3131-3814>>),  
Michael Fogleman [ctb, cph]

**Maintainer** Tyler Morgan-Wall <[tylermw@gmail.com](mailto:tylermw@gmail.com)>

**Repository** CRAN

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triangulate\_matrix      *Triangulate a Height Map*

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### Description

Uses Delaney triangulation to approximate a rectangular height field (in matrix form) with constraints (either maximum allowable error, or a maximum number of triangles). Increasing the error limit will result in a coarser approximation, but fewer triangles in the model. For many models (particularly those with large, flat regions or smooth changes in height), this can result in significant reductions in model size with no perceptual loss in terrain surface quality.

### Usage

```
triangulate_matrix(
  heightmap,
  maxError = 1e-04,
  maxTriangles = 0,
  y_up = TRUE,
  start_index = 1,
  verbose = FALSE
)
```

### Arguments

heightmap	A two-dimensional matrix, where each entry in the matrix is the elevation at that point. All points are assumed to be evenly spaced.
maxError	Default '0.0001'. Maximum error allowed in triangulating the height map.
maxTriangles	Default '0', which turns off this setting (and only uses the 'max_error' arg). Otherwise, specifies the maximum number of triangles when triangulating the height map.
y_up	Default 'TRUE'. Which axis is "upwards" in the return matrix. If 'FALSE', 'z' is up.
start_index	Default '1'. The offset to the first 'x' and 'z' indices.
verbose	Default 'FALSE'. Prints reduction in number of triangles/max error.

### Value

Returns a matrix of vertices and IDs for each triangle.

### Examples

```
#Let's triangulate the built-in `volcano` dataset.

#Helper function to plot polygons over an `image()` plot.
plot_polys = function(tri_matrix) {
  #reverse orientation for `image`
```

```
    tri_matrix[,3] = max(tri_matrix[,3])-tri_matrix[,3]+1
    for(i in seq_len(nrow(tri_matrix)/3)) {
      polypath(tri_matrix[(3*(i-1)+1):(3*i), c(1,3)])
    }
  }

#Here, we don't accept any error, but still triangulate
tris = triangulate_matrix(volcano, maxError = 0, verbose = TRUE)
image(x=1:nrow(volcano), y = 1:ncol(volcano), volcano)
plot_polys(tris)

#Let's increase the allowable error:
tris = triangulate_matrix(volcano, maxError = 1, verbose = TRUE)
image(x=1:nrow(volcano), y = 1:ncol(volcano), volcano)
plot_polys(tris)

#Increase it again
tris = triangulate_matrix(volcano, maxError = 10, verbose = TRUE)
image(x=1:nrow(volcano), y = 1:ncol(volcano), volcano)
plot_polys(tris)

#Here, we set an allowable number of triangles instead, using exactly 20 triangles:
tris = triangulate_matrix(volcano, maxTriangles = 20, verbose = TRUE)
image(x=1:nrow(volcano), y = 1:ncol(volcano), volcano)
plot_polys(tris)

#The output of this function can be passed directly to `rgl::triangles3d()` for plotting in 3D.
```

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